inf303 - Fuzzy Control and Artificial Neural Networks in Robotics and Automation

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<th>Module label</th>
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Contact person

- Module responsibility
  - Sergei Fatikow
  - Die im Modul Lehrenden

- Authorized examiners
  - Sergei Fatikow
  - Die im Modul Lehrenden

Entry requirements

Skills to be acquired in this module

Experts in different branches try to approach their application-specific control and information processing problems by using fuzzy logic and artificial neural networks (ANN). The experiences gathered up to now prove robotics and automation technology to be predestined fields of application of both these approaches. The major topics of the course are control problems in robotics and automation technology, principles of fuzzy logic and ANN and their practical applications, comparison of conventional and advanced control methods, combination of fuzzy logic and ANN in control systems. The course gives a comprehensive treatment of these advanced approaches for interested students.

Professional competence

The students:

- recognise control problems in robotics and automation technology,
- name principles of fuzzy logic and ANN and their practical applications,
- compare conventional and advanced control methods,
- characterise the combination of fuzzy logic and ANN in control systems

Methodological competence

The students:

- will acquire knowledge of the tools, methods and applications in fuzzy logic and ANN
- deepen their knowledge for the practical use of the given methods
- can use common software tools for design and application of fuzzy logic and ANN

Social competence

The students:

- gain experience in interdisciplinary work
- are integrated into the recent research work

Objective of the module / skills:

Self-competence

The students:

- are able to transfer the gained knowledge for later use in their theses or studies for AMiR
- can Design (complex) fuzzy logic controller and ANN systems
• reflect their (control) solutions by using methods learned in this course

Module contents

• Control problems in robotics and automation technology
• Basic ideas of fuzzy logic and ANN
• Principles of fuzzy logic
• Fuzzy logic of rule-based systems
• ANN models
• ANN learning rules
• Multilayer perceptron networks and backpropagation
• Associative networks
• Self-organizing feature maps
• PID design principles
• Design of fuzzy control systems
• Fuzzy logic application examples
• Design of ANN control systems
• ANN application examples
• Fuzzy + Neuro: principles and applications

Reader’s advisory

Essential:

• Lecture notes (available at the secretariat, A1-3-303) in book form

Recommended:

• Kahlert, J.: Fuzzy Control für Ingenieure, Vieweg, Braunschweig Wiesbaden, 1995
• Zell, A.: Simulation Neuronaler Netze, Addison-Wesley / Oldenbourg Verlag, Bonn, 1996

Secondary Literature:

• Altrock, M. O. R.: Fuzzy Logic, R. Oldenbourg Verlag, 1993
• Kahlert, J. und Hubert, F.: Fuzzy-Logik und Fuzzy-Control, Vieweg, 1993
• Kratzer, K.P.: Neuronale Netze, Carl Hanser, 1993
• Lawrence, J.: Neuronale Netze, Systhema Verlag, München, 1992
• Omidvar, O. and van der Smagt, P. (eds.): Neural Networks for Robotics, Academic Press, 1997
• Patterson, D.W.: Künstliche neuronale Netze, Prentice Hall, 1996
• Pham, D.T. a200
• nd Liu, X.: Neural Networks for Identification, Prediction and Control, Springer, 1997
• Rigoll, G.: Neuronale Netze, Expert Verlag, Renningen-Malmshausen, 1994
• Schulte, U.: Einführung in Fuzzy-Logik, Franzis-Verlag, München, 1993
• von Altrock, C.: Fuzzy Logic: Technologie, Oldenbourg, 1993
• Zakharov, S. Ladewig-Riebler, P. und Thoer, St.: Neuronale Netze für Ingenieure, Vieweg, Wiesbaden, 1998
• Zimmermann H.-J. (Hrsg.): Datenanalyse, VDI-Verlag, 1995
• Zimmermann, H.-J. (Hrsg.): Neuro + Fuzzy: Technologien und Anwendungen, VDI-Verlag,
1995

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