inf307 - Robotics

Module label       Robotics
Module code        inf307
Credit points      6.0 KP
Workload           180 h

Used in course of study
- Master's Programme Computing Science > Nicht Informatik
- Master's Programme Computing Science > Technische Informatik
- Master's Programme Embedded Systems and Microrobotics > Akzentsetzungsmodul
- Master's Programme Engineering of Socio-Technical Systems > Embedded Brain Computer Interaction
- Master's Programme Engineering of Socio-Technical Systems > Human-Computer Interaction
- Master's Programme Engineering of Socio-Technical Systems > Systems Engineering

Contact person
Module responsibility
- Andreas Hein
- Die im Modul Lehrenden

Entry requirements

Skills to be acquired in this module

Professional competence
The students:
- Name and know the functions and applications of robot systems
- Characterise the basic concepts to program robot systems
- Differentiate between the interaction of mechanical, electrical and software components

Methodological competence
The students:
- Define characteristics and components of robot systems for a specific application
- Design and implement robot system sub-components
- Design and parameterise simple control structures
- Plan the application of robot systems and derive the requirements
- Model electrical and mechanical systems
- Develop and realise simple robot systems

Social competence
The students:
- Solve robot systems problems in team work

Self-competence
The students:
- Reflect their solutions in reference to robot system methods

Module contents

- Integration in production plants / aims / subsystems
- Architectures / classifications (classification of robots)
- Robot components + Computer systems for programming
  - PA-10
  - Lego Mindstorms
- Basics of kinematics
  - Coordinate transformation, homogeneous coordinates, Coordinate transitions
  - Kinematic equation systems, transformation of vectors
- Kinematic
  - Joint types (manipulators) / Wheels, TCP
- Denavit-Hartenberg-Transformation
- Forward calculation
- Backward calculation

- Sensors
  - General properties of sensors, parameter
  - Simple optical position sensors
  - Inductive-, capacitive- und ultrasonic-sensors
  - Distance sensors (laser scanner, triangulation sensors)
  - Force sensors
  - Sensor data preparation

- Planning / Regulation
  - Overall regulation approach, terms, process- and control functions, PID-controller
  - Planning concepts and approaches (On-Line, Off-Line), planning processes, construction and path planning

- Actuators

Reader's advisory

essential:
lecture notes

recommended:

secondary literature:

Links
Languages of instruction
German, English

Duration (semesters)
1 Semester

Module frequency
once a year

Module capacity
unlimited

Modullevel
AS (Akzentsetzung / Accentuation)

Modulart
Pflicht o. Wahlpflcht / compulsory or optional

Lern-/Lehrform / Type of program
V+Ü

Vorkenntnisse / Previous knowledge

Examination
Time of examination
Type of examination
Portfolio: Hands-on exercises, report, and written or oral exam

Final exam of module
At the end of the lecture period

Course type
Comment
SWS
Frequency
Workload attendance
Lecture
3.00
SuSe
42 h
Exercises
1.00
SuSe
14 h

Total time of attendance for the module
56 h